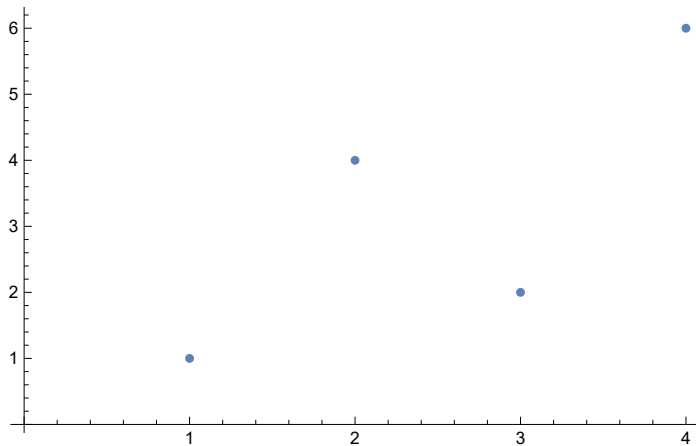


```

signal = {1, 4, 2, 6};
N = Length[signal];
ListPlot[signal]

```



## FED cycle

Pad the border with 0.

$$\Delta_s[j_] := \begin{cases} -1 * s[[j]] + s[[j+1]] & j == 1 \\ s[[j-1]] - 1 * s[[j]] & j == N; \\ s[[j-1]] - 2 * s[[j]] + s[[j+1]] & \text{True} \end{cases}$$

Function which is responsible for the varying step size depending on the current iteration  $i$  and the length of the box filter  $n$  (the total length is  $2n+1$ ).

$$\tau[i_, n_] := \frac{1}{4 * \text{Cos}[\pi * \frac{2*i+1}{4*n+2}]^2};$$

The first theorem states a similarity between the box filter and one FED cycle. Apply a box filter with  $n = 1$ :

```

signalBox = ListConvolve[{1/3, 1/3, 1/3},
  ArrayPad[signal, 1, "Reversed"]
] // N
{2., 2.33333, 4., 4.66667}

```

Now calculate one FED cycle by hand. The result is indeed the same.

```

 $\tau[0, 1]$ 

```

$$\frac{1}{3}$$

```

sDiv = Table[ $\Delta_{\text{signal}}[j]$ , {j, 1, N}]

```

```

signal +  $\tau[0, 1]$  * sDiv // N

```

```

{3, -5, 6, -4}

```

```

{2., 2.33333, 4., 4.66667}

```

Test also with a box filter of length  $n = 2$ . The cyclic FED seems to be identical to a reversed convolution

```

ArrayPad[signal, 2, "Reversed"]

```

```

{4, 1, 1, 4, 2, 6, 6, 2}

```

```

signalBox2 = ListConvolve[{1/5, 1/5, 1/5, 1/5, 1/5}, ArrayPad[signal, 2, "Reversed"]] // N

```

```

{2.4, 2.8, 3.8, 4.}

```

```

signal +  $\tau[0, 2]$  * sDiv +  $\tau[1, 2]$  * Table[ $\Delta_{(\text{signal} + \tau[0,2] * \text{sDiv})}[j]$ , {j, 1, N}] // N

```

```

{2.4, 2.8, 3.8, 4.}

```

In this case two iterations are needed and the derivative of the derivative needs to be calculated (expansion is done by hand). But, the result is still identical.

```
signal + τ[0, 2] * sDiv + τ[1, 2] * sDiv + τ[0, 2] * τ[1, 2] * Table[ΔsDiv[j], {j, 1, N}] // N
{2.4, 2.8, 3.8, 4.}
```

## Matrix notation

It is also possible to write the problem in matrix-vector notation. In this case the vector is the input signal and the matrix is built in such a ways that it also encodes the second order derivative.

$$A = \text{Table}\left[\begin{array}{ll} -1 & i == 1 \&\& j == 1 \mid i == N \&\& j == N \\ -2 & i == j \\ 1 & i == j + 1 \mid j == i + 1 \\ 0 & \text{True} \end{array}, \{i, 1, N\}, \{j, 1, N\}\right];$$

```
A // MatrixForm
```

$$\begin{pmatrix} -1 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & -1 \end{pmatrix}$$

```
(IdentityMatrix[N] + τ[0, 1] * A).signal // N
```

```
{2., 2.33333, 4., 4.66667}
```

```
(IdentityMatrix[N] + τ[1, 2] * A). (IdentityMatrix[N] + τ[0, 2] * A).signal // N
```

```
{2.4, 2.8, 3.8, 4.}
```

Ordering doesn't matter.

```
(IdentityMatrix[N] + τ[0, 2] * A). (IdentityMatrix[N] + τ[1, 2] * A).signal // N
```

```
{2.4, 2.8, 3.8, 4.}
```

Multiple iterations:

```
FED[n_] := Module[{iter},
  iter = ConstantArray[0, n + 1];
  iter[[1]] = signal;

  Do[
    iter[[i + 2]] = (IdentityMatrix[N] + τ[i, n] * A).iter[[i + 1]]
    , {i, 0, n - 1}];

  iter
]
```

```
N[FED[10]]
```

```
{{1., 4., 2., 6.}, {1.75421, 2.74298, 3.50842, 4.99438}, {2.01428, 2.68424, 3.69794, 4.60354},
{2.20757, 2.78341, 3.66675, 4.34227}, {2.39952, 2.88591, 3.59748, 4.11709},
{2.59845, 2.978, 3.51897, 3.90458}, {2.80355, 3.06523, 3.43502, 3.6962},
{3.00971, 3.1504, 3.34946, 3.49043}, {3.19655, 3.2279, 3.27233, 3.30322},
{3.28677, 3.26552, 3.23337, 3.21434}, {3.04762, 3.14286, 3.38095, 3.42857}}
```

```
boxLength = 10;
```

```
signalBox10 = ListConvolve[ConstantArray[ $\frac{1}{2 * \text{boxLength} + 1}$ , 2 * boxLength + 1],
```

```
ArrayPad[signal,  $\left\lfloor \frac{2 * \text{boxLength} + 1}{2} \right\rfloor$ , "Reversed"]] // N
```

```
{3.04762, 3.14286, 3.38095, 3.42857}
```

```
Table[{i, i}, {i, 1, Length[signal]}]
```

```
{{1, 1}, {2, 2}, {3, 3}, {4, 4}}
```

```

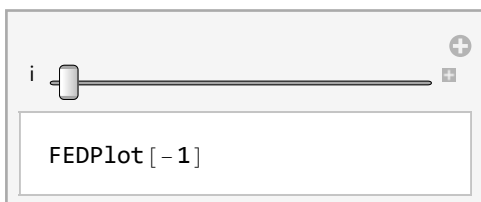
FEDPlot[i_] := Show[
  ListLinePlot[FED[10][[i + 2]] // N,
    PlotRange → {{0.9, 4.1}, {0, 6.1}},
    PlotLegends → { { None
                    { "FED:  $B_{21} \cdot \hat{u}$  (i = " <> IntegerString[i, 10] <> ") " True }
                    }
                    i == -1 },
    AxesLabel → {"uj", "*"},
    PlotStyle → { Directive[Blue, Opacity[0]] i == -1
                { Blue True },
    PlotMarkers → {Graphics@{Blue, Disk[]}, 0.03},
    ImageSize → 500,
    BaseStyle → {FontSize → 14},
    Ticks → {Table[{j, j}, {j, 1, Length[signal]}], Automatic},
    LabelStyle → Directive[FontSize → 14]
  ],
  ListLinePlot[signalBox10,
    PlotStyle → Blue,
    PlotLegends → {"Box:  $\tilde{B}_{2 \cdot n+1} * \hat{u} = \tilde{B}_{21} * \hat{u}$ "},
    PlotMarkers → {Graphics@{Blue, Disk[]}, 0.03},
    LabelStyle → Directive[FontSize → 14]
  ],
  ListLinePlot[signal,
    PlotStyle → Directive[Gray, Opacity[0.4]],
    PlotLegends → {"Signal  $\hat{u}$ "},
    PlotMarkers → {Graphics@{Gray, Rectangle[]}, 0.03},
    LabelStyle → Directive[FontSize → 14]
  ]
];

```

```

Manipulate[
  FEDPlot[i]
, {i, -1, boxLength - 1, 1}]

```



```

(*Export[FileNameJoin[{NotebookDirectory[],"frames/i=0.png"}],
  Table[FEDPlot[i],{i,-1,9}], "VideoFrames", Antialiasing→True];*)

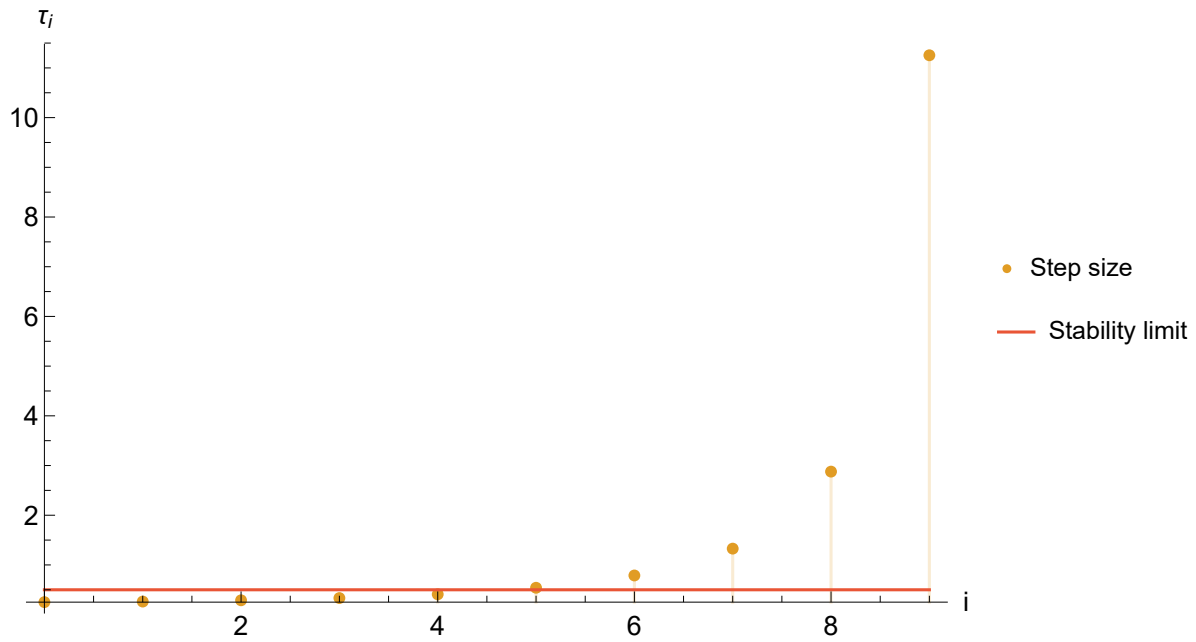
```

```

Show[
  DiscretePlot[τ[i, boxLength], {i, 0, boxLength - 1},
    PlotLabel → "n = " <> ToString[boxLength],
    PlotRange → Full,
    ImageSize → 500,
    BaseStyle → {FontSize → 14},
    AxesLabel → {"i", "τi"},
    PlotStyle → Blue,
    PlotLegends → {"Step size"}
  ],
  Plot[1/2, {x, 0, boxLength - 1}, PlotStyle → Red, PlotLegends → {"Stability limit"}]
]

```

n = 10



```

cumTimes = Round[Flatten[{Table[ $\sum_{i=0}^{n-1} \tau[i, \text{boxLength}]$ ], {n, 1, 10}],
 $\sum_{i=0}^{10-1} \tau[i, \text{boxLength}] + \text{Table}[\sum_{i=0}^{n-1} \tau[i, \text{boxLength}], \{n, 1, 10\}]$ ], 0.01] // N
{0.25, 0.51, 0.8, 1.14, 1.55, 2.09, 2.87, 4.2, 7.08, 18.33,
18.58, 18.85, 19.14, 19.47, 19.88, 20.42, 21.21, 22.53, 25.41, 36.67}

```

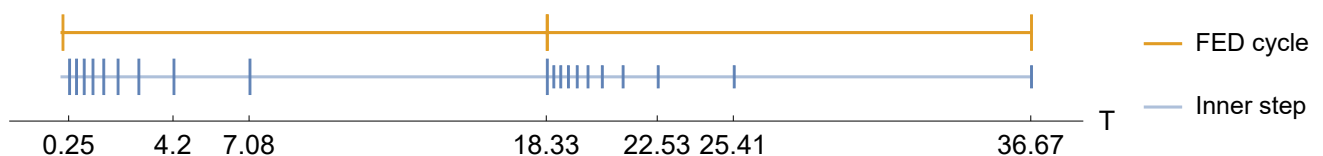
```
Show[
(* Left part *)
NumberLinePlot[{{Table[ $\sum_{i=0}^{n-1} \tau[i, \text{boxLength}]$ , {n, 1, 10}], Interval[{0,  $\sum_{i=0}^{10-1} \tau[i, \text{boxLength}]$ ]}},
    Ticks -> {{cumTimes[[1]], cumTimes[[8]], cumTimes[[9]],
        cumTimes[[10]], cumTimes[[18]], cumTimes[[19]], cumTimes[[20]]}},
    ImageSize -> Large,
    PlotRange -> {-2, 2 + 2 * cumTimes[[10]]},
    AxesLabel -> {"T"},
    BaseStyle -> {FontSize -> 14},
    PlotLegends -> LineLegend[{None, ■}, {None, "FED cycle"}],
    LabelStyle -> Directive[FontSize -> 14],
    PlotStyle -> {Directive[Opacity[1]], Opacity[0]}
] /. {Point[pos_] := Rectangle[{pos[[1]], pos[[2]] - 0.4}, {pos[[1]] + 0.07, pos[[2]] + 0.4}]},

(* Left yellow part *)
NumberLinePlot[{None, Interval[{0,  $\sum_{i=0}^{10-1} \tau[i, \text{boxLength}]$ ]}]},
    PlotStyle -> {Opacity[1], Opacity[1]}
] /. {Point[pos_] := Rectangle[{pos[[1]], pos[[2]] - 0.4}, {pos[[1]] + 0.07, pos[[2]] + 0.4}]},

(* Right blue part *)
NumberLinePlot[{cumTimes[[10]] + Table[ $\sum_{i=0}^{n-1} \tau[i, \text{boxLength}]$ , {n, 1, 10}], None},
    PlotStyle -> {Opacity[1], Opacity[1]}
] /. {Point[pos_] := Rectangle[{pos[[1]], pos[[2]] - 0.25}, {pos[[1]] + 0.07, pos[[2]] + 0.25}]},

(* Right yellow part *)
NumberLinePlot[{None, Interval[{cumTimes[[10]], cumTimes[[10]] +  $\sum_{i=0}^{10-1} \tau[i, \text{boxLength}]$ ]}]},
    PlotStyle -> {Opacity[1], Opacity[1]}
] /. {Point[pos_] := Rectangle[{pos[[1]], pos[[2]] - 0.4}, {pos[[1]] + 0.07, pos[[2]] + 0.4}]},

(* Blue line *)
NumberLinePlot[{Interval[{0, cumTimes[[-1]]]}]},
    PlotStyle -> {Opacity[0.5]},
    PlotLegends -> {"Inner step"}
] /. {Point[pos_] := Rectangle[{0, 0}, {0, 0}]}
]
```



## Leja Ordering

To improve numerical stability the step sizes  $\tau_i$  are re-ordered. For how Leja Ordering works, see also section 2.3 from <http://www.mia.uni-saarland.de/Publications/breuss-pp273.pdf>

```
steps = Table[ $\tau[i, 11]$ , {i, 0, 10}] // N
{0.25117, 0.260795, 0.281577, 0.317122, 0.374566,
 0.468059, 0.627712, 0.926037, 1.57507, 3.43452, 13.4834}
```

$$\text{stepsI} = \frac{1}{\text{steps}}$$

```
{3.98137, 3.83442, 3.55142, 3.15336, 2.66976,
 2.13648, 1.59309, 1.07987, 0.634894, 0.291161, 0.0741654}
```

```
stepsIReordered = {stepsI[[1]], stepsI[[11]], stepsI[[6]], stepsI[[8]], stepsI[[4]],
  stepsI[[10]], stepsI[[3]], stepsI[[7]], stepsI[[2]], stepsI[[9]], stepsI[[5]]}
```

```
{3.98137, 0.0741654, 2.13648, 1.07987, 3.15336,
 0.291161, 3.55142, 1.59309, 3.83442, 0.634894, 2.66976}
```

For the default ordering the values do not match.

```
Do[
```

```
  Print[ $\prod_{k=0}^j \text{Abs}[\text{stepsI}[[j+1+1]] - \text{stepsI}[[k+1]]]$ ]
```

```
, {j, 0, Length[stepsI] - 2}]
```

```
0.146949
```

```
0.121676
```

```
0.224478
```

```
0.651323
```

```
2.40352
```

```
9.5693
```

```
35.3127
```

```
102.46
```

```
189.027
```

```
156.517
```

```
Do[
```

```
  Print[
```

```
    Max[ $\left(\prod_{k=0}^j \text{Abs}[\#1 - \text{stepsI}[[k+1]]]\right) \& /@ \text{stepsI}$ ]
```

```
  ]
```

```
, {j, 0, Length[stepsI] - 2}]
```

```
3.90721
```

```
14.6921
```

```
51.0882
```

```
157.311
```

```
408.314
```

```
842.075
```

```
1279.05
```

```
1286.34
```

```
721.289
```

```
156.517
```

But when the Leja Ordering is applied, the values do match

```
Do[
```

```
  Print[ $\prod_{k=0}^j \text{Abs}[\text{stepsIReordered}[[j+1+1]] - \text{stepsIReordered}[[k+1]]]$ ]
```

```
, {j, 0, Length[stepsIReordered] - 2}]
```

```
3.90721
```

```
3.80475
```

3.08326

5.3758

3.33573

6.78523

4.02452

3.95586

9.70491

7.46948

```

Do[
  Print[
    Max[ $\left(\prod_{k=0}^j \text{Abs}[\#1 - \text{stepsIReordered}[[k + 1]]]\right) \& /@ \text{stepsIReordered}$ 
    ]
  , {j, 0, Length[stepsIReordered] - 2}]

```

3.90721

3.80475

3.08326

5.3758

3.33573

6.78523

4.02452

3.95586

9.70491

7.46948